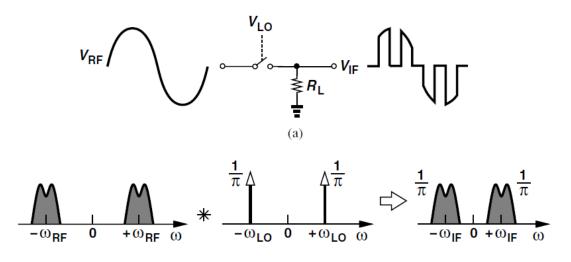
RF Mixers (II)

Passive Mixers

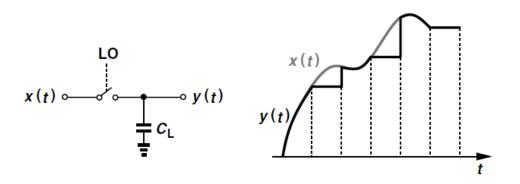
- "Return-to-Zero" Implementations:



Conversion Gain: How about single-balanced and double-balanced?

RX mixers are not very common in modern RF design.

- "Non-Return-to-Zero" (Sampling) Mixers: Case I: Voltage-Driven



Conversion Gain Calculation:

$$|Y_1(f) + Y_2(f)|_{IF} = \sqrt{\frac{1}{\pi^2} + \frac{1}{4}} [|X(f - f_{LO})| + |X(f + f_{LO})|]$$

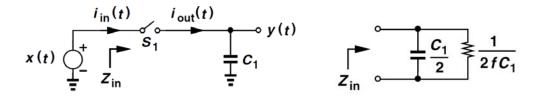
How about single-balanced and double-balanced?

B. Razavi HO #2

Noise Calculation:

$$\overline{V_{n,in,SB}^2} = \frac{kT}{2\left(\frac{1}{\pi^2} + \frac{1}{4}\right)} \left(3.9R_1 + \frac{1}{2C_1 f_{LO}}\right)$$

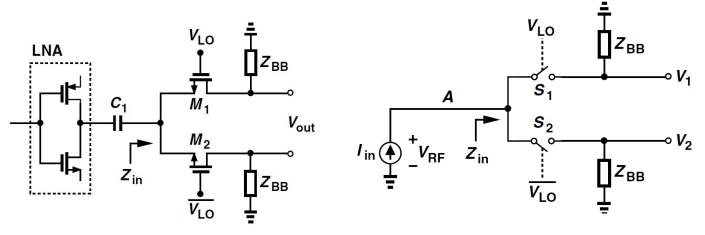
Input impedance for $\omega \sim \omega_{LO}$:



How about single-balanced and double-balanced?

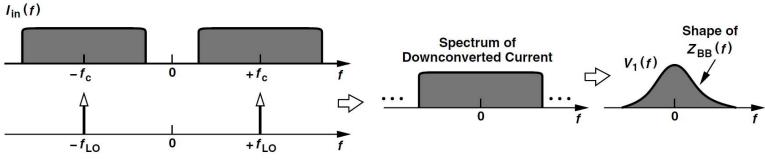
- Flicker Noise: Passive mixers generate little flicker noise in the baseband output if the transistors do not enter saturation at any point during the cycle and carry no dc current.

Case II: Current-Driven



1. Assume a certain frequency response for Z_{BB}:

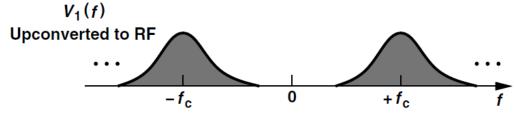




VLO

C

3. Now the baseband signal is mixed with LO and returns to node A:



 \rightarrow The baseband impedance is "translated" to f_c.

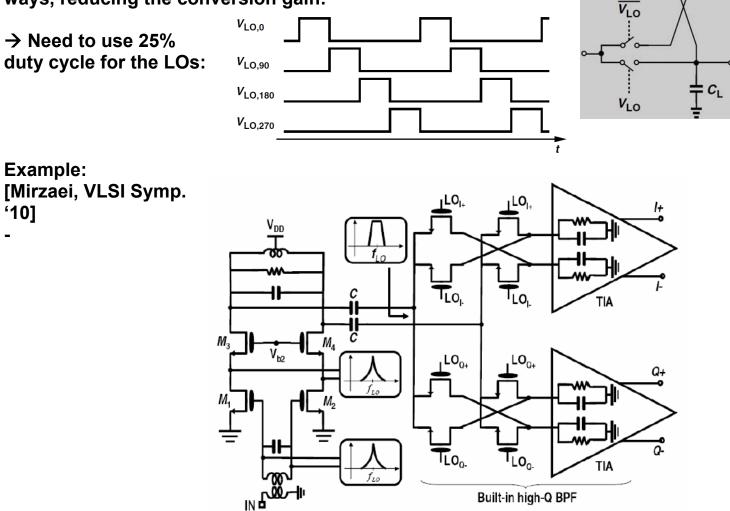
 \rightarrow Can obtain very high Qs in RF!

Noise and Nonlinearity:

Since the switches are in series with a <u>current source</u>, they should contribute negligible noise and nonlinearity. In practice, though, some corruption occurs.

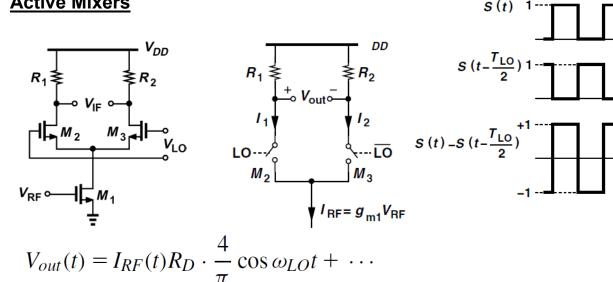
Problem of Current Division:

In a double-balanced mixer, the input current would split two ways, reducing the conversion gain:

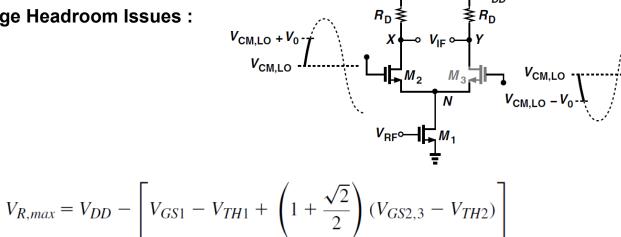


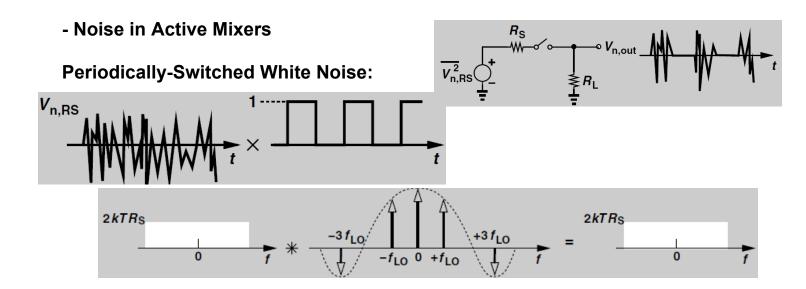
Active Mixers





- Conversion Gain :
- Voltage Headroom Issues :



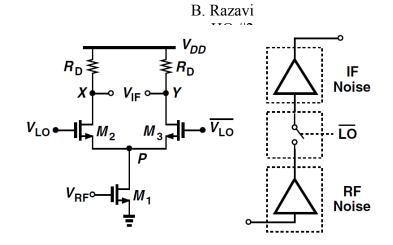


Observations: 1. Noise current of M1 is periodically-switched.

2. R_D's directly add noise to IF.

3. M2 and M3 contribute noise for only a fraction of the period.

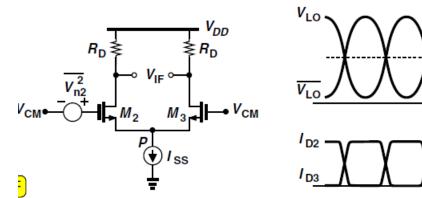
If only 1 and 2 are considered:

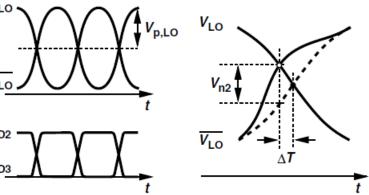


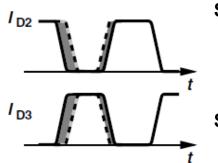
$$\overline{V_{n,X}^2} = \frac{1}{2} \left(\overline{I_{n,M1}^2} \right) R_D^2 + 4kTR_D$$
$$\overline{V_{n,in}^2} = \pi^2 kT \left(\frac{\gamma}{g_{m1}} + \frac{2}{g_{m1}^2 R_D} \right)$$

Referred to the input:

Flicker Noise in Active Mixers:







Step 1:

 $V_{CM} + V_{p,LO} \sin \omega_{LO}t + V_{n2}(t) = V_{CM} - V_{p,LO} \sin \omega_{LO}t$

Step 2:

$$|\Delta T| = \frac{|V_{n2}(t)|}{2V_{p,LO}\omega_{LO}}$$

Step 3:

$$I_{n,out}(t) = \sum_{k=-\infty}^{+\infty} \frac{2I_{SS}V_{n2}(t)}{S_{LO}} \delta\left(t - k\frac{T_{LO}}{2}\right) \qquad V_{n,out}(f)|_{k=0} = \frac{I_{SS}R_{D}}{\pi V_{p,LO}} V_{n2}(f)$$